L Number	Hits	Search Text	DB	Time stamp
1	29	(offset same utc same clock) and gps	USPAT; US-PGPUB; IBM_TDB	2004/07/14 10:12
2	1	(offset same utc same clock same imag$4) and gps	USPAT; US-PGPUB; IBM_TDB	2004/07/14 09:35
4	1	"09/900321" and offset	USPAT; US-PGPUB; IBM_TDB	2004/07/14 09:41
5	1	(offset same utc same clock same (video image camera))	USPAT; US-PGPUB; IBM_TDB	2004/07/14 09:58
6	9634	(offset same time same (video image camera))	USPAT; US-PGPUB; IBM_TDB	2004/07/14 09:58
7	10	((offset same time same (video image camera))) same geograph$4	USPAT; US-PGPUB; IBM_TDB	2004/07/14 09:58
8	2919428	imag$4 same geograph$4 same (offset difference$3 deviat$4) time	USPAT; US-PGPUB; IBM_TDB	2004/07/14 10:13
9	41	imag$4 same geograph$4 same (offset difference$3 deviat$4) same time	USPAT; US-PGPUB; IBM_TDB	2004/07/14 10:17
10	11	imag$4 same geograph$4 same ((offset difference$3 deviat$4) near2 time)	USPAT; US-PGPUB; IBM_TDB	2004/07/14 10:22
11	1	("6282362").PN.	USPAT; US-PGPUB; IBM_TDB	2004/07/14 10:23
12	1	(("6282362").PN.) and gps	USPAT; US-PGPUB; IBM_TDB	2004/07/14 10:28
13	0	(("6282362").PN.) and (gps near4 clock)	USPAT; US-PGPUB; IBM_TDB	2004/07/14 10:26
14	0	synchro$6 near5 gps near4 reciever$2 near4 clock near4 imag$4	USPAT; US-PGPUB; IBM_TDB	2004/07/14 10:27
15	0	gps near4 reciever$2 near4 clock near4 imag$4	USPAT; US-PGPUB; IBM_TDB	2004/07/14 10:27
16	1	(("6282362").PN.) and clock	USPAT; US-PGPUB; IBM_TDB	2004/07/14 10:28
17	0	synchroniz$4 and (("6282362").PN.)	USPAT; US-PGPUB; IBM_TDB	2004/07/14 10:29
18	18	synchroniz$4 same gps same receiver same clock same (camera ccd video image)	USPAT; US-PGPUB; IBM_TDB	2004/07/14 12:05
19	258	gps adj1 receiver adj1 (clock time)	USPAT; US-PGPUB; IBM_TDB	2004/07/14 11:49
20	1	(gps adj1 receiver adj1 (clock time)) with (imag$4 video camera ccd)	USPAT; US-PGPUB; IBM_TDB	2004/07/14 11:48
21	1	(gps adj1 receiver adj1 (clock time)) same (imag$4 video camera ccd)	USPAT; US-PGPUB; IBM_TDB	2004/07/14 11:50
22	36	(gps adj1 receiver adj1 (clock time)) with synchroniz$4	USPAT; US-PGPUB; IBM_TDB	2004/07/14 11:49
23	3	((gps adj1 receiver adj1 (clock time)) with synchroniz$4) and (imag$4 video camera ccd)	USPAT; US-PGPUB; IBM_TDB	2004/07/14 12:50
24	53	synchroniz$4 same gps same clock same (camera ccd video image)	USPAT; US-PGPUB; IBM_TDB	2004/07/14 12:15

25	8345	imag$4 near3 record$4 near5 (clock time)	USPAT; US-PGPUB; IBM_TDB	2004/07/14 12:16
26	13	(imag$4 near3 record$4 near5 (clock time)) with (GPS (global adj1 position$4))	USPAT; US-PGPUB; IBM_TDB	2004/07/14 12:20
27	1	("5296884").PN.	USPAT; US-PGPUB; IBM_TDB	2004/07/14 12:20
28	1	(("5296884").PN.) and clock	USPAT; US-PGPUB; IBM_TDB	2004/07/14 12:22
29	0	(("5296884").PN.) and synchro$7	USPAT; US-PGPUB; IBM_TDB	2004/07/14 12:27
30	1	("6366311").PN.	USPAT; US-PGPUB; IBM_TDB	2004/07/14 12:27
31	1	(("6366311").PN.) and synchro$5	USPAT; US-PGPUB; IBM_TDB	2004/07/14 12:27
32	1	(("6366311").PN.) and (synchro$5 same (clock time))	USPAT; US-PGPUB; IBM_TDB	2004/07/14 12:28
33	1	"09/900321" and synchro$5	USPAT; US-PGPUB; IBM_TDB	2004/07/14 12:51
34	1	"09/900321" and synchro$7	USPAT; US-PGPUB; IBM_TDB	2004/07/14 12:54
35	25	synchro$7 near5 clock near5 utc	USPAT; US-PGPUB; IBM_TDB	2004/07/14 16:09
36	0	(synchro$7 near5 clock near5 utc) same camera	USPAT; US-PGPUB; IBM_TDB	2004/07/14 12:55
37	8	(synchro$7 near5 clock near5 utc) same gps	USPAT; US-PGPUB; IBM_TDB	2004/07/14 14:46
38	284	((camera video ccd imag$4) near2 (clock time)) same (gps utc)	USPAT; US-PGPUB; IBM_TDB	2004/07/14 14:46
39	37	(((camera video ccd imag$4) near2 (clock time)) same (gps utc)) same (synchroniz$4 adjust$4 correct$4)	USPAT; US-PGPUB; IBM_TDB	2004/07/14 14:51
40	1	("6337683").PN.	USPAT; US-PGPUB; IBM_TDB	2004/07/14 14:51
3	1	"09/900321"	USPAT; US-PGPUB; IBM_TDB	2004/07/14 15:52
41	2	"09/888208"	USPAT; US-PGPUB; IBM_TDB	2004/07/14 16:21
42	1	("6282362").PN.	USPAT; US-PGPUB; IBM_TDB	2004/07/14 16:27
43	1	(("6282362").PN.) and display$4	USPAT; US-PGPUB; IBM_TDB	2004/07/14 16:13
44	1	(("6282362").PN.) and (display$4 with time)	USPAT; US-PGPUB; IBM_TDB	2004/07/14 16:13
45	0	"09/888208" and (record$4 near5 imag$4)	USPAT; US-PGPUB; IBM_TDB	2004/07/14 16:22
46	0	"09/888208" and (record$4 with imag$4)	USPAT; US-PGPUB; IBM_TDB	2004/07/14 16:22
47	2	"09/888208" and (record$4 with video)	USPAT; US-PGPUB; IBM_TDB	2004/07/14 16:23

48	1	(("6282362").PN.) and (record$4 with (video imag$4))	USPAT; US-PGPUB; IBM_TDB	2004/07/14 16:23
49	3	(("6282362").PN.) or "09/888208"	USPAT; US-PGPUB; IBM_TDB	2004/07/14 16:27
50	0	((("6282362").PN.) or "09/888208") and utc	USPAT; US-PGPUB; IBM_TDB	2004/07/14 16:28
51	0	((("6282362").PN.) or "09/888208") and utc	USPAT; US-PGPUB; IBM_TDB	2004/07/14 16:28
52	0	(("6282362").PN.) and utc	USPAT; US-PGPUB; IBM_TDB	2004/07/14 16:30
53	3	((("6282362").PN.) or "09/888208") and time	USPAT; US-PGPUB; IBM_TDB	2004/07/14 16:32
54	2	((("6282362").PN.) or "09/888208") and (time with synchroniz$4)	USPAT; US-PGPUB; IBM_TDB	2004/07/14 16:35
55	2	((("6282362").PN.) or "09/888208") and (interpolat$5)	USPAT; US-PGPUB; IBM_TDB	2004/07/14 16:37
56	0	((("6282362").PN.) or "09/888208") and (interpolat$5 same epoch)	USPAT; US-PGPUB; IBM_TDB	2004/07/14 16:37
57	0	((("6282362").PN.) or "09/888208") and (interpolat$5 same file)	USPAT; US-PGPUB; IBM_TDB	2004/07/14 16:38
58	0	((("6282362").PN.) or "09/888208") and (interpolat$5 same log)	USPAT; US-PGPUB; IBM_TDB	2004/07/14 16:38
59	2	((("6282362").PN.) or "09/888208") and (interpolat$5)	USPAT; US-PGPUB; IBM_TDB	2004/07/14 16:46
60	3	((("6282362").PN.) or "09/888208") and (longitude latitude)	USPAT; US-PGPUB; IBM_TDB	2004/07/14 17:07
61	0	((("6282362").PN.) or "09/888208") and (tag$5)	USPAT; US-PGPUB; IBM_TDB	2004/07/14 17:08

DOCUMENT-IDENTIFIER: US 20020057217 A1

TITLE: GPS based tracking system

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Brief Description of Drawings Paragraph - DRTX (15):

[0030] FIG. 14 is a flow chart describing the process of **synchronizing GPS time and video time**.

Detail Des

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TITLE: Spherical surveillance system architecture

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Detail Description Paragraph - DETX (94):

[0098] The video broadcast protocol is divided into two sections: the logical layer which describes what data is sent, and the network encoding layer, which describes how that data is encoded and broadcast on the network. Preferably, software components are used to support both broadcast and receipt of the network-encoded data. Time synchronization is achieved by time stamping individual video broadcast packets with a common time stamp (e.g., **UTC time) for the video** frame. Network Time Protocol (NTP) is used to **synchronize** system clocks via a time synchronization channel

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TITLE: System and method for creating, storing, and utilizing composite images of a geographic location

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TITLE: System and method for creating, storing, and utilizing composite images of a geographic location

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TX (21):

[0051] In step 72, a time interval T is measured in the image sequence between the two passings of the landmark. In step 74, the computer 28 uses the **GPS** data to compute a function for determining the time interval between successive passes of any point along the path. The function is then used to find, for each point x on the path, a time of return Tr(x) which measures the lapse of time between the two passings of each point. In step 76, a point is identified for which Tr(x)=T. The identified point provides the **GPS** position of the landmark and hence, a **GPS** time associated with the landmark. Given the **GPS** time, a difference between the **GPS time and the video time** associated with the landmark may be calculated for **synchronizing** any image frame acquired at a particular **video time to the GPS** position of the camera at a particular **GPS** time.

Detail Description Paragraph - DE

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TITLE: GPS based tracking system

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Brief Description of Drawings Paragraph - DRTX (15):

[0030] FIG. 14 is a flow chart describing the process of **synchronizing GPS time and video time**.

Detail Description Paragraph - DETX (164):

[0184] Tsync computer 534 is used to **synchronize video time to GPS** time. Tsync 534 is connected to a Trimble Pallisades **GPS** receiver 536, VITC reader 535 and VITC 506. FIG. 14 is a flowchart describing the operation of Tsync 534. **GPS** receiv